# **Vector-Valued Functions**

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#### **Vector-valued functions**

Let *I* be a subset of **R**. Then a **vectorvalued function** is a rule **r** that assigns to every real number *t* in *I* a unique vector in  $\mathbb{R}^n$ .

$$\mathbf{r}(t) = \langle x_1(t), x_2(t), \dots, x_n(t) \rangle$$

For example, for n = 3:

$$\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$$

NOTE: Domain is a subset of real numbers and range is  $\mathbb{R}^3$ .

### Limits and continuity of vector-valued functions

If  $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$ , then  $\lim_{t \to a} \mathbf{r}(t) = \langle \lim_{t \to a} f(t), \lim_{t \to a} g(t), \lim_{t \to a} h(t) \rangle$ provided the limit of the component functions exist.

**Definition:** A vector-valued function  $\mathbf{r}$  is **continuous at** a if

$$\lim_{t \to a} \mathbf{r}(t) = \mathbf{r}(a)$$

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# **Definition of Derivative**

# The derivative $\mathbf{r}'$ is defined by

$$\frac{d\mathbf{r}}{dt} = \mathbf{r}'(t) = \lim_{h \to 0} \frac{\mathbf{r}(t+h) - \mathbf{r}(t)}{h}$$

The vector  $\mathbf{r}'(t)$  is called the **tangent vector** to the curve defined by  $\mathbf{r}$ .

#### Computing the derivative

**Theorem:** If  $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle \rangle$ , where f, g and h are differentiable functions, then

$$\mathbf{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

# **Differentiation Rules**

**Theorem:** Suppose that  $\mathbf{r}$  and  $\mathbf{s}$  are differentiable vector functions, c a scalar, and f a real-valued function.

1. 
$$\frac{d}{dt}[\mathbf{r}(t) + \mathbf{s}(t)] = \mathbf{r}'(t) + \mathbf{s}'(t)$$
  
2. 
$$\frac{d}{dt}[c\mathbf{r}(t)] = c \mathbf{r}'(t)$$
  
3. 
$$\frac{d}{dt}[f(t)\mathbf{r}(t)] = f'(t)\mathbf{r}(t) + f(t)\mathbf{r}'(t)$$
  
4. 
$$\frac{d}{dt}[\mathbf{r}(t) \cdot \mathbf{s}(t)] = \mathbf{r}'(t) \cdot \mathbf{s}(t) + \mathbf{r}(t) \cdot \mathbf{s}'(t)$$
  
5. 
$$\frac{d}{dt}[\mathbf{r}(t) \times \mathbf{s}(t)] = \mathbf{r}'(t) \times \mathbf{s}(t) + \mathbf{r}(t) \times \mathbf{s}'(t)$$
  
6. 
$$\frac{d}{dt}[\mathbf{r}(f(t))] = f'(t)\mathbf{r}'(f(t))$$

# **Definite Integrals**

The **definite integral** of a continuous vector function  $\mathbf{r}(t)$  can be computed using

$$\int_{a}^{b} \mathbf{r}(t) dt = \left\langle \int_{a}^{b} f(t) dt, \int_{a}^{b} g(t) dt, \int_{a}^{b} h(t) dt \right\rangle$$

# Definition of a path

Let I = [a, b] be a closed interval for some numbers a < b.  $I \subseteq \mathbb{R}$ .

**Definition:** A path in  $\mathbb{R}^n$  is a continuous function  $\mathbf{r} : I \to \mathbb{R}^n$  where  $\mathbf{r}(a)$  and  $\mathbf{r}(b)$  are the **endpoints** of the path  $\mathbf{r}$ .

#### Velocity, speed and acceleration

Let  $\mathbf{r}: I \to \mathbb{R}^n$  be a differentiable path. Then

- The velocity  $\mathbf{v}(t) = \mathbf{r}'(t)$ .
- The speed is  $||\mathbf{v}(t)||$ .
- The acceleration is a(t) = v'(t) = r''(t).

# The tangent line

Let  $\mathbf{r} : I \to \mathbb{R}^n$  be a path and  $\mathbf{v}(t_0) \neq \mathbf{0}$ . Then the parametric equation of the tangent line at  $t_0$  to the path  $\mathbf{r}$  is

$$\mathbf{l}(t) = \mathbf{r}(t_0) + (t - t_0)\mathbf{v}_0.$$

#### Length of a path

**Definition:** The length  $L(\mathbf{r})$  of a differentiable path  $\mathbf{r} : [a, b] \to \mathbb{R}^n$  is the integral of its speed

$$L(\mathbf{r}) = \int_a^b \|\mathbf{r}'(t)\| dt$$