## Worksheet for April 24

MATH 24 — Spring 2014

## Sample Solutions

Consider the system of linear equations

$$3x_2 - 6x_3 + 6x_4 + 4x_5 = -5, 3x_1 - 7x_2 + 8x_3 - 5x_4 + 8x_5 = 9, 3x_1 - 9x_2 + 12x_3 - 9x_4 + 6x_5 = 15.$$

1.- Let A be the matrix of coefficients of this system, form the augmented matrix  $(A \mid I_3)$ , and convert it into row echelon form using a sequence of elementary row operations.

*Solution* — There are many ways to achieve this. Here is one sequence of row operations that works:

$\int 0$	3	-6	6	4	1	0	0	
3	-7	8	-5	8	0	1	0	
$\sqrt{3}$	-9	12	-9	6	0	0	1	Ϊ

(i) Add -1 times the third row from the second:

$\int 0$	3	-6	6	4	1	0	0	
0	2	-4	4	2	0	1	-1	
3	-9	12	-9	6	0	0	1	)

(ii) Exchange the first and third rows:

(iii) Add -3/2 times the second row to the third:

$$\left(\begin{array}{ccccc|c} 3 & -9 & 12 & -9 & 6 & 0 & 0 & 1 \\ 0 & 2 & -4 & 4 & 2 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 1 & 1 & -3/2 & 3/2 \end{array}\right)$$

Note that the augmented part accumulates the product of the three elementary matrices corresponding to the operations above:

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & -3/2 & 3/2 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -3/2 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

2.– Suppose you obtained ( $B \mid C$ ) after part 1. Solve the system

$$B\begin{pmatrix} x_1\\ x_2\\ x_3\\ x_4\\ x_5 \end{pmatrix} = C\begin{pmatrix} -5\\ 9\\ 15 \end{pmatrix}.$$

Check that your solutions are also solutions of the original system of linear equations.

*Solution* — From the above, we have the system:

$$3x_1 - 9x_2 + 12x_3 - 9x_4 + 6x_5 = 15$$
  

$$2x_2 - 4x_3 + 4x_4 + 2x_5 = -6$$
  

$$x_5 = 4.$$

This system has infinitely many solutions, one of which is  $s_0 = (-24, -7, 0, 0, 4)$ . The other solutions are of the form  $s_0 + s_h$  where  $s_h$  is in the null space of left multiplication by B.

Because C is invertible, with inverse

$$C^{-1} = \begin{pmatrix} 0 & 3/2 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix},$$

and B = CA, the two systems have the exact same solutions. Indeed, if  $B(x_1, x_2, x_3, x_4, x_5) = (15, -6, 4)$  then

$$A\begin{pmatrix} x_1\\ x_2\\ x_3\\ x_4\\ x_5 \end{pmatrix} = C^{-1}B\begin{pmatrix} x_1\\ x_2\\ x_3\\ x_4\\ x_5 \end{pmatrix} = C^{-1}\begin{pmatrix} 15\\ -6\\ 4 \end{pmatrix} = \begin{pmatrix} -5\\ 9\\ 15 \end{pmatrix}.$$

Indeed, if  $A(x_1, x_2, x_3, x_4, x_5) = (-5, 9, 15)$  then

$$B\begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \\ x_{5} \end{pmatrix} = CA \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \\ x_{5} \end{pmatrix} = C \begin{pmatrix} -5 \\ 9 \\ 15 \end{pmatrix} = \begin{pmatrix} 15 \\ -6 \\ 4 \end{pmatrix}.$$

If you have multiple systems Ax = b to solve, each with the same coefficient matrix but different target vectors b, this process is a very economical way to solve all of them. Indeed, Cb is easy to compute and, since B is in echelon form, the equivalent system Bx = Cb is easy to solve. However, if you only have one system Ax = b to solve, finding an echelon form for the augmented matrix  $(A \mid b)$  as described in section 3.4 is not any longer.

3.- Continue from the echelon form for A you obtained in part 1 and find the *reduced* row echelon form of A using some more elementary row operations.

Solution — After some steps, we obtain that the reduced row echelon form of A is

$$\begin{pmatrix} 1 & 0 & -2 & 3 & 0 \\ 0 & 1 & -2 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} -5 & 9 & 26/3 \\ -1 & 2 & -2 \\ 1 & -3/2 & 3/2 \end{pmatrix} A.$$

4.– Looking at the reduced row echelon form of A you obtained in part 3, explain how you can reach the conclusion that

$$\begin{pmatrix} -6\\8\\12 \end{pmatrix} = -2 \begin{pmatrix} 0\\3\\3 \end{pmatrix} - 2 \begin{pmatrix} 3\\-7\\-9 \end{pmatrix}$$
$$\begin{pmatrix} 6\\-5\\-9 \end{pmatrix} = 3 \begin{pmatrix} 0\\3\\3 \end{pmatrix} + 2 \begin{pmatrix} 3\\-7\\-9 \end{pmatrix}.$$

and

Solution — From the reduced row echelon form of A, we see that the homogeneous system Ax = 0 is equivalent to the simple system

$$x_1 = 2x_3 - 3x_4, x_2 = 2x_3 - 2x_4, x_5 = 0.$$

Choosing  $x_3 = -1, x_4 = 0$ , we obtain the solution  $(-2, -2, -1, 0, 0) = -2e_1 - 2e_2 - e_3$ , which means that

$$-2Ae_1 - 2Ae_2 - Ae_3 = 0 \quad \text{or} \quad Ae_3 = -2Ae_1 - 2Ae_2.$$

Since  $Ae_1, Ae_2, Ae_3$  are the first three columns of A, we obtain

$$\begin{pmatrix} -6\\8\\12 \end{pmatrix} = -2 \begin{pmatrix} 0\\3\\3 \end{pmatrix} - 2 \begin{pmatrix} 3\\-7\\-9 \end{pmatrix}.$$

Choosing  $x_3 = 0, x_4 = -1$ , we obtain the solution  $(3, 2, 0, -1, 0) = 3e_1 + 2e_2 - e_4$ , which means that

 $3Ae_1 + 2Ae_2 - Ae_4 = 0$  or  $Ae_4 = 3Ae_1 + 2Ae_2$ .

Since  $Ae_1, Ae_2, Ae_3$  are the first, second and fourth columns of A, we obtain

$$\begin{pmatrix} 6\\-5\\-9 \end{pmatrix} = 3 \begin{pmatrix} 0\\3\\3 \end{pmatrix} + 2 \begin{pmatrix} 3\\-7\\-9 \end{pmatrix}.$$

This process is completely general: looking at the reduced row echelon form B of a  $m \times n$  matrix A, if the *i*-th column  $Be_i$  has no pivot then the entries of  $Be_i$  spell out a way to write the *i*-th column  $Ae_i$  as a linear combination of columns  $Ae_1, \ldots, Ae_{i-1}$ . It follows from this that the columns of A that correspond to pivots in B generate the column space span $\{Ae_1, Ae_2, \ldots, Ae_n\}$ . In fact, they always form a basis for the column space since the rank of A equals the number of pivots in B.