## Math 24 Spring 2012 Friday, April 13

- 1. Assume V and W are finite-dimensional vector spaces with ordered bases  $\beta$  and  $\gamma$  respectively, and T and U are linear transformations from V to W. TRUE or FALSE?
  - (a) For any scalar a, aT + U is a linear transformation from V to W. (T)
  - (b)  $[T]^{\gamma}_{\beta} = [U]^{\gamma}_{\beta}$  implies that T = U. (T)
  - (c) If  $m = \dim(V)$  and  $n = \dim(W)$  then  $[T]^{\gamma}_{\beta}$  is an  $m \times n$  matrix. (F) (It's  $n \times m$ .)
  - (d)  $[T + U]^{\gamma}_{\beta} = [T]^{\gamma}_{\beta} + [U]^{\gamma}_{\beta}$ . (T)
  - (e)  $\mathcal{L}(V, W) = \mathcal{L}(W, V)$ . (F) (They do have the same dimension, mn.)
  - (f) If  $m = \dim(V)$  then the function  $f: V \to F^m$  defined by  $f(v) = [v]_\beta$  is a linear transformation from V to  $F^m$ . (T)
  - (g) Every element of  $M_{3\times 3}(\mathbb{R})$  is the matrix of some linear transformation from  $\mathbb{R}^3$  (with the standard ordered basis) to  $P_2(\mathbb{R})$  (with the standard ordered basis). (T)
  - (h) If  $T : \mathbb{R}^2 \to \mathbb{R}^2$  is a linear transformation such that  $[T]^{\beta}_{\beta} = \begin{pmatrix} 2 & 4 \\ 1 & 0 \end{pmatrix}$ , where  $\beta$  is the standard ordered basis for  $\mathbb{R}^2$ , then T(1, -1) = (1, 4). (F)

Here is the computation from that last item. The standard ordered basis is  $\beta = \{e_1, e_2\} = \{(1, 0), (0, 1)\}.$ 

The columns of the matrix, therefore, are the coordinates of the images the vectors in  $\beta$ , that is, the coordinates of  $T(e_1)$  and  $T(e_2)$ .

Because the ordered basis of the codomain is  $\beta$ , when we say "coordinates" in the previous sentence, we mean " $\beta$  coordinates." That is, we see from  $[T]^{\beta}_{\beta}$  that

$$[T(e_1)]_{\beta} = \begin{pmatrix} 2\\ 1 \end{pmatrix}$$
 and  $[T(e_2)]_{\beta} = \begin{pmatrix} 4\\ 0 \end{pmatrix}$ 

Because the designated codomain basis vectors are  $e_1$  and  $e_2$ , this tells us that

$$T(e_1) = 2e_1 + 1e_2 = (2, 1)$$
 and  $T(e_2) = 4e_1 + 0e_2 = (4, 0).$ 

Therefore, because T is linear, we can write

$$T(1,-1) = T(e_1 - e_2) = T(e_1) - T(e_2) = (2,1) - (4,0) = (-2,1).$$

2. Let  $T: P_2(\mathbb{R}) \to P_3(\mathbb{R})$  be defined as follows:

If p(x) is a polynomial in  $P_2(x)$ , then T(p(x)) is the antiderivative q(x) of p(x) such that q(0) = 0. Another way to say this is

$$T(p(x)) = \int_0^x p(t) \, dt.$$

If  $\beta = \{1, x, x^2\}$  and  $\gamma = \{1, x, x^2, x^3\}$  are the standard bases for  $P_2(\mathbb{R})$  and  $P_3(\mathbb{R})$ , find the matrix  $[T]_{\beta}^{\gamma}$ .

The columns of  $[T]^{\gamma}_{\beta}$  are the  $\gamma$ -coordinates of the images of the basis vectors in  $\beta$ . The basis vectors in  $\beta$  are  $\{1, x, x^2\}$ .

Their images are T(1) = x,  $T(x) = \frac{1}{2}x^2$ ,  $T(x_2) = \frac{1}{3}x^3$ .

To find the columns of the matrix, we write these vectors out as linear combinations of the vectors in  $\gamma$ , which gives us their  $\gamma$ -coordinates:

$$T(1) = x = (0)1 + (1)x + (0)x^{2} + (0)x^{3},$$
  

$$T(x) = \frac{1}{2}x^{2} = (0)1 + (0)x + \frac{1}{2}x^{2} + (0)x^{3},$$
  

$$T(x^{2}) = \frac{1}{3}x^{3} = (0)1 + (0)x + (0)x^{2} + \frac{1}{3}x^{3}.$$
  

$$[T(1)]_{\gamma} = \begin{pmatrix} 0\\1\\0\\0\\1\\2\\0 \end{pmatrix}, \ [T(x)]_{\gamma} = \begin{pmatrix} 0\\0\\1\\2\\0\\1\\3 \end{pmatrix}, \ [T(x^{2})]_{\gamma} = \begin{pmatrix} 0\\0\\0\\1\\3\\3 \end{pmatrix}.$$

These coordinate vectors are the columns of the matrix.

$$[T]^{\gamma}_{\beta} = \begin{pmatrix} 0 & 0 & 0\\ 1 & 0 & 0\\ 0 & \frac{1}{2} & 0\\ 0 & 0 & \frac{1}{3} \end{pmatrix}.$$

- 3. Let  $\beta = \{(1,0), (0,1)\}$  and  $\gamma = \{(1,1), (1,-1)\}$  be two ordered bases for  $\mathbb{R}^2$ .
  - (a) Find:

$$[(1,1)]_{\beta} = \begin{pmatrix} 1\\1 \end{pmatrix}$$
$$[(1,-1)]_{\beta} = \begin{pmatrix} 1\\-1 \end{pmatrix}$$

(b) Find:

$$[(1,0)]_{\gamma} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$$
$$[(0,1)]_{\gamma} = \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \end{pmatrix}$$

- (c) Recall that I denotes the identity function,  $I(\vec{v}) = \vec{v}$ . Find the matrices:
  - $$\begin{split} [I]_{\beta}^{\beta} &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ [I]_{\gamma}^{\gamma} &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ [I]_{\beta}^{\gamma} &= \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix} \\ [I]_{\gamma}^{\beta} &= \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \end{split}$$

- 4. Let  $T : \mathbb{R}^2 \to \mathbb{R}^2$  and  $U : \mathbb{R}^2 \to \mathbb{R}^2$  be linear transformations. Let  $\beta = \{(1,0), (0,1)\}$  be the standard ordered basis for  $\mathbb{R}^2$ .
  - (a) If T(1,0) = (a,c) and T(0,1) = (b,d), then find:

$$T(x,y) = (ax + by, \, cx + dy)$$

$$[T]^{\beta}_{\beta} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

(b) If  $U(x,y) = (\overline{a}x + \overline{b}y, \overline{c}x + \overline{d}y)$ , then find :

$$U(1,0) = (\overline{a}, \,\overline{c})$$

$$U(0,1) = (\overline{b}, \overline{d})$$

$$[U]^{\beta}_{\beta} = \begin{pmatrix} \overline{a} & \overline{b} \\ \overline{c} & \overline{d} \end{pmatrix}$$

(c) The composition of U and T is denoted  $T \circ U$ , or simply TU, and is defined by TU(x, y) = T(U(x, y)). For T as in part (a) and U as in part (b), find:

$$TU(1,0) = T(\overline{a}, \overline{c}) = (a\overline{a} + b\overline{c}, c\overline{a} + d\overline{c})$$

$$TU(0,1) = T(\overline{b}, \overline{d}) = (a\overline{b} + b\overline{d}, c\overline{b} + d\overline{d})$$

$$[TU]^{\beta}_{\beta} == \begin{pmatrix} a\overline{a} + b\overline{c} & a\overline{b} + b\overline{d} \\ c\overline{a} + d\overline{c} & c\overline{b} + d\overline{d} \end{pmatrix}$$

In the next section of the text, you will see matrix multiplication defined. This is where the definition comes from. Matrix multiplication is defined so that if A is the matrix of T and B is the matrix of U, then AB is the matrix of TU. You have just come up with the formula for the product of two  $2 \times 2$  matrices. 5. This an extra problem, not really part of our Math 24 study.

If we think of function composition as a kind of multiplication, then if V is a vector space over a field F, the collection  $\mathcal{L}(V)$  of linear transformations from V to itself has an addition operation and a multiplication operation. (We know that  $\mathcal{L}(V)$  is closed under these operations; the sum of linear functions is linear and the composition of linear functions is linear.)

With these two operations, is  $\mathcal{L}(V)$  a field? If not, which of the field axioms hold, and which do not?

I'll leave this one as a challenge.

This algebraic structure turns out to obey many of the field axioms, but not all of them. It is not a field but it is a *ring*. The ring axioms include many but not all of the field axioms.

The field axioms:

- (F1) (a) Adddition is commutative.
  - (b) Multiplication is commutative.
- (F2) (a) Adddition is associative.
  - (b) Multiplication is associative.
- (F3) (a) There is an additive identity element.
  - (b) There is a multiplicative identity element.
- (F4) (a) Every element has an additive inverse.
  - (b) Every element except the additive identity has an multiplicative inverse.
- (F5) Multiplication distributes over addition.