

Worksheet #21

(1) Consider the first order system

$$x' = \begin{bmatrix} -\frac{3}{2} & 1 \\ -\frac{1}{4} & -\frac{1}{2} \end{bmatrix} x$$

- Find the general solution and describe the behavior as $t \rightarrow \infty$.

1st find eigenvalues.

$$\begin{vmatrix} -3/2 - \lambda & 1 \\ -1/4 & -1/2 - \lambda \end{vmatrix} = (-3/2 - \lambda)(-1/2 - \lambda) + 1/4$$

$$= (3/4 + (3/2 + 1/2)\lambda + \lambda^2) + 1/4$$

$$= \lambda^2 + 2\lambda + 1 = (\lambda + 1)^2$$

$\rightarrow \lambda = -1$ is a repeated eigenvalue.

Now eigenvector

$$\begin{bmatrix} -3/2 + 1 & 1 \\ -1/4 & -1/2 + 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} -1/2 & 1 \\ -1/4 & 1/2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$\rightarrow x_1 = 2x_2$ let $x_2 = 1$ $\bar{w} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

- Draw a few trajectories.

other vector, \bar{y} (generalized eigenvector)

is the solution of $(A - \lambda I)\bar{y} = \bar{w}$

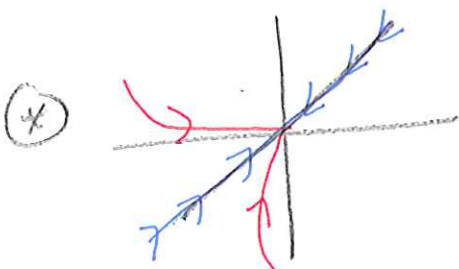
$$\begin{bmatrix} -1/2 & 1 \\ -1/4 & 1/2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\rightarrow y_1 - 2y_2 = -4 \quad \text{let } y_2 = 0.$$

$$y_1 = -4$$

$$\bar{y} = \begin{pmatrix} -4 \\ 0 \end{pmatrix}$$

\rightarrow General soln is $\bar{x}(t) = c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^{-t} + c_2 e^{-t} \left[t \begin{pmatrix} 2 \\ 1 \end{pmatrix} + \begin{pmatrix} -4 \\ 0 \end{pmatrix} \right]$



(2) Consider the first order system

$$x' = \begin{bmatrix} 3 & -2 \\ 4 & -1 \end{bmatrix} x$$

- Find the general solution and describe the behavior as $t \rightarrow \infty$.

Eigenvalues $\begin{vmatrix} 3-\lambda & -2 \\ 4 & -1-\lambda \end{vmatrix} = (3-\lambda)(-1-\lambda) + 8$

$$= \lambda^2 + (-3+1)\lambda - 3 + 8$$

$$= \lambda^2 - 2\lambda + 5 = 0$$

$$\lambda = \frac{2 \pm \sqrt{4-4(5)}}{2} = 1 \pm 2i$$

Eigenvectors for $\lambda = 1+2i$

$$\begin{bmatrix} 3-(1+2i) & -2 \\ 4 & -1-(1+2i) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2-2i & -2 \\ 4 & -2-2i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\textcircled{1} = \frac{2+2i}{8} \textcircled{1} \quad \begin{bmatrix} 1 & -\frac{1}{4}(2+2i) \\ 4 & -2-2i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \textcircled{2} = \textcircled{2} - 4\textcircled{1} \quad \begin{bmatrix} 1 & -\frac{1}{4}(2+2i) \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

- Draw a few trajectories.

$$x_1 = \frac{1}{4}(2+2i)x_2$$

$$\text{let } x_2 = 4$$

$$\bar{w} = \begin{pmatrix} 2+2i \\ 4 \end{pmatrix}$$

look at $\bar{w} e^{\lambda t} = \begin{pmatrix} 2+2i \\ 4 \end{pmatrix} e^t e^{2it}$

collect real & imaginary parts.

$$e^t \begin{pmatrix} 2+2i \\ 4 \end{pmatrix} (\cos 2t + i \sin 2t)$$

$$\cong e^t \left[\begin{pmatrix} 2 \cos 2t & -2 \sin 2t \\ 4 \cos 2t \end{pmatrix} + i \begin{pmatrix} 2 \cos 2t & +2 \sin 2t \\ 4 \sin 2t \end{pmatrix} \right]$$

$$x(t) = c_1 e^t \begin{pmatrix} 2 \cos 2t & -2 \sin 2t \\ 4 \cos 2t \end{pmatrix} + c_2 e^t \begin{pmatrix} 2 \cos 2t & +2 \sin 2t \\ 4 \sin 2t \end{pmatrix}$$

Trajectories for #2.

