

Last class

Today's material

Solution for linear first order  
systems

Finding solutions

Next class

# Math 23, Spring 2007

## Lecture 17

Scott Pauls

Department of Mathematics  
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5/4/07

# Material from last class

Math 23, Spring  
2007

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Last class

Today's material

Solution for linear first order  
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Next class

- ▶ First order systems of equations
- ▶ Linear algebra review
- ▶ Eigenvalues and Eigenvectors

# Linear first order systems

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$$x_1' = p_{11}(t)x_1 + \cdots + p_{1n}(t)x_n + g_1(t)$$

$$x_2' = p_{21}(t)x_1 + \cdots + p_{2n}(t)x_n + g_2(t)$$

$\vdots$

$$x_n' = p_{n1}(t)x_1 + \cdots + p_{nn}(t)x_n + g_n(t)$$

Rewrite this in matrix form:

$$\vec{x}' = P(t)\vec{x} + \vec{g}(t)$$

The system is *homogeneous* if  $\vec{g}$  is the zero vector.

We will write a solution to this system as

$$\vec{x} = \vec{\phi}(t) = \begin{pmatrix} \phi_1(t) \\ \vdots \\ \phi_n(t) \end{pmatrix}$$

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# Linear first order systems

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Principle of superposition

## Theorem

*If  $\vec{\phi}(t)$  and  $\vec{\psi}(t)$  are solutions to a homogeneous linear first order system, then any linear combination is also a solution.*

## Theorem

*A set of solutions to a first order linear system,  $\{\vec{\phi}_1(t), \dots, \vec{\phi}_n(t)\}$  are linearly independent at  $t$  if*

$$W(\vec{\phi}_1(t), \dots, \vec{\phi}_n(t)) = \det \begin{pmatrix} \phi_{11}(t) & \dots & \phi_{1n}(t) \\ \vdots & \vdots & \vdots \\ \phi_{n1}(t) & \dots & \phi_{nn}(t) \end{pmatrix} \neq 0$$

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# Linear first order systems

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## Theorem

*If  $\{\vec{\phi}_1(t), \dots, \vec{\phi}_n(t)\}$  are linearly independent solutions to a linear first order homogeneous system for  $\alpha < t < \beta$ , then every solution to the system may be uniquely written as a linear combination of the  $\vec{\phi}_i$ .*

## Theorem

*If  $\{\vec{\phi}_1(t), \dots, \vec{\phi}_n(t)\}$  are solutions to a linear first order homogeneous system on the interval  $\alpha < t < \beta$  then  $W(\vec{\phi}_1(t), \dots, \vec{\phi}_n(t))$  is either identically zero on this interval or it never vanishes.*

# Methods for finding solutions

## Phase planes and phase portraits

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$$\vec{x}' = A\vec{x}$$

where  $A$  is an  $n \times n$  matrix.

Cases:

$n=1$ : this is a single linear first order equation  $x' = ax$ .

Methods of solution: Direction fields, integrating factors

$n=2$ : this is a pair of linear equations

$$x' = ax + by$$

$$y' = cx + dy$$

Draw phase plane/portrait. Use `ppplane7.m`.



# Methods for finding solutions

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$$\vec{x}' = A\vec{x}$$

Idea: mimic solutions for second order equations, guess

$$\vec{x} = \vec{\xi}e^{rt}$$

Plug into the equation:

$$r\vec{\xi}e^{rt} = A\vec{\xi}e^{rt}$$

Divide through by  $e^{rt}$  and rewrite as

$$(A - rI)\vec{\xi} = 0$$

Conclusion: solutions of this form are determined by the eigenvalues and eigenvectors of  $A$ .

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# Example

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$$\vec{x}' = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix} \vec{x}$$

# Work for next class

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- ▶ Read 7.6
- ▶ Homework 6 is due Monday 5/7/07