Lecture 5: Homogeneous, inhomogeneous, solution sets. Applications

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- Finish up with homogeneous equations, learning when they have a nontrivial solution.
- Obscribe the solution set homogeneous equation as the span of a finite set of vectors.
- Obscribe the solution set of an inhomogeneous equation.
- Use systems of linear equations to model economic behavior.
- Use systems of linear equations to model street traffic.

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Trivial and nontrivial solutions

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A homogeneous system $A\mathbf{x} = \mathbf{0}$ always has at least one solution: $\mathbf{x} = \mathbf{0}$. If we form the linear combination of the columns of A with all weights equal to 0, we just get $\mathbf{0} + \mathbf{0} + \ldots + \mathbf{0} = \mathbf{0}$.

The interesting question becomes: can we find $\mathbf{x} \neq \mathbf{0}$ with $A\mathbf{x} = \mathbf{0}$?

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Let $A\mathbf{x} = \mathbf{0}$ be a homogeneous system of linear equations. The **trivial solution** to this system is $\mathbf{x} = \mathbf{0}$. A solution \mathbf{x} to $A\mathbf{x} = \mathbf{0}$ with $\mathbf{x} \neq \mathbf{0}$ is referred to as a **non-trivial solution**.

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Trivial and nontrivial solutions: examples

Example

Let
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$$A\begin{bmatrix}1\\0\\1\end{bmatrix} = 1\begin{bmatrix}1\\0\end{bmatrix} + 0\begin{bmatrix}0\\2\end{bmatrix} + 1\begin{bmatrix}-1\\0\end{bmatrix} = \begin{bmatrix}0\\0\end{bmatrix}$$

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Let $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \end{bmatrix}$. Is there a nontrivial solution to $A\mathbf{x} = \mathbf{0}$?Reduce the augmented matrix to echelon form: $\begin{bmatrix} 1 & 2 & 3 & 0 \\ 2 & 4 & 5 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & -1 & 0 \end{bmatrix}$.

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Is every column a pivot column? No, so the solution is not unique, and there is a nontrivial solution to $A\mathbf{x} = \mathbf{0}$. In this example, $\mathbf{x} = (-2, 1, 0)$ is a nontrivial solution.

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$$2x - 4y - 8z = 0$$

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$$(x, y, z) = (2y + 4z, y, z) = y(2, 1, 0) + z(4, 0, 1).$$

Thus the solution set is

$$\mathsf{Span}\{(2,1,0),(4,0,1)\}.$$

Parametric vector equations

In the previous example, every solution to the system

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has the form

$$(x, y, z) = c(2, 1, 0) + d(4, 0, 1)$$

for some choice of scalars $c, d \in \mathbb{R}$.

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The system

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The system

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has the solution set $\{(x, x)\} = \text{Span}\{(1, 1)\} \subset \mathbb{R}^2$. It has the parametric equation $\mathbf{x} = x(1, 1)$, where x is a scalar.

We have a pretty good idea of how to describe the solution set of $A\mathbf{x} = \mathbf{0}$ in parametric form.

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Example Describe the solution set of $A\mathbf{x} = \mathbf{b}$ where $A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$ and $\mathbf{b} = (3, 6)$. The augmented matrix is $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \end{bmatrix}$. Now write x + 2y = 3, solve for the basic variable x, to get x = 3 - 2y, y free.

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Theorem

Let $A\mathbf{x} = \mathbf{b}$ be an inhomogeneous matrix equation, where A is a $m \times n$ matrix and $\mathbf{b} \neq \mathbf{0}$. Suppose that \mathbf{p} is a particular solution to the system. Consider the homogeneous system $A\mathbf{z} = \mathbf{0}$. Then every other solution \mathbf{w} of $A\mathbf{x} = \mathbf{b}$ has the form

$$\mathbf{w} = \mathbf{p} + \mathbf{v}$$

where **v** is some solution to $A\mathbf{z} = \mathbf{0}$.

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Proof.

Suppose that $A\mathbf{w} = \mathbf{b} = A\mathbf{p}$. Then we can subtract to obtain

$$A(\mathbf{w} - \mathbf{p}) = \mathbf{b} - \mathbf{b} = \mathbf{0}.$$

So $\mathbf{w} - \mathbf{p} = \mathbf{v}$ for some \mathbf{v} a solution of $A\mathbf{z} = \mathbf{0}$

Now suppose that **p** is a particular solution to $A\mathbf{x} = \mathbf{b}$ and $A\mathbf{v} = \mathbf{0}$.

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- find one particular solution \mathbf{p} , that is a vector \mathbf{p} such that $A\mathbf{p} = \mathbf{b}$;
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The previous theorem shows that to describe the solutions of $A\mathbf{x} = \mathbf{b}$ takes two steps:

- find one particular solution p, that is a vector p such that Ap = b;
- **2** describe all solutions to the affiliated homogeneous system $A\mathbf{z} = \mathbf{0}$

The solutions set is then $\{\mathbf{p} + \mathbf{v} : A\mathbf{v} = \mathbf{0}\}$.

Write all solutions to

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. Thus the general parametric form of the solution to the inhomogeneous is

$$\begin{array}{c}
1\\
0\\
+t
\end{array}
\begin{bmatrix}
-2\\
1\\
0
\end{bmatrix}$$

where t is allowed to be any real number.

Now we're going to look at some applications of linear systems: economics and street traffic.

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We denote the output of the three sectors by p_C, p_E, p_S .

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.0	.4	.6	С
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Rewriting these in linear form we obtain

$$p_C - .4p_E - .6p_S = 0$$

 $-.6p_C + .9p_E - .2p_S = 0$
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We solve this by row reduction on the augmented matrix

$$\left[\begin{array}{rrrrr}1 & -.4 & -.6 & 0\\ -.6 & .9 & -.2 & 0\\ -.4 & -.5 & .8 & 0\end{array}\right]$$

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$$\left[\begin{array}{rrrrr}1 & -.4 & -.6 & 0\\ -.6 & .9 & -.2 & 0\\ -.4 & -.5 & .8 & 0\end{array}\right] \sim \left[\begin{array}{rrrrr}1 & 0 & -.94 & 0\\ 0 & 1 & -.85 & 0\\ 0 & 0 & 0 & 0\end{array}\right]$$

The solution is therefore $p_C = .94p_S$, $p_E = .85p_S$, and p_S free.

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The solution is therefore $p_C = .94p_S$, $p_E = .85p_S$, and p_S free. The price vector is

$$\mathbf{p} = \begin{bmatrix} p_C \\ p_E \\ p_S \end{bmatrix} = p_S \begin{bmatrix} .94 \\ .85 \\ 1 \end{bmatrix}$$

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The mathematical framework of *networks* is useful in many different contexts.

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Streets can be used as an example of networks:

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Node (intersection)		Flow in		Flow out	
A	3	00 + 500	=	$x_1 + x_2$	
В		$x_2 + x_4$	=	$300 + x_3$	
С	1	00 + 400	=	$x_4 + x_5$	
D		$x_1 + x_5$	=	600	
			• •		

Dan Crytser Lecture 5: Homogeneous, inhomogeneous, solution sets. Applica-

We have the balanced flow equations

Node (intersection)	Flow in		Flow out
A	300 + 500	=	$x_1 + x_2$
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We also need that the flow into the system (500 + 300 + 100 + 400) equals the flow out $(300 + x_3 + 600)$.

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D	$x_1 + x_5$	=	600

We also need that the flow into the system (500 + 300 + 100 + 400) equals the flow out $(300 + x_3 + 600)$. We simplify and combine all of this into a system of equations:

$$x_{1} + x_{2} = 800$$

$$x_{2} - x_{3} + x_{4} = 300$$

$$x_{4} + x_{5} = 500$$

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$$\begin{array}{rl} x_1 + x_2 & = 800 \\ x_2 - x_3 + x_4 & = 300 \\ x_4 + x_5 & = 500 \\ x_1 & + x_5 & = 600 \\ x_3 & = 400 \end{array}$$

If we solve this system with row reduction we get the solution set

$$\begin{cases} x_1 = 600 - x_5 \\ x_2 = 200 + x_5 \\ x_3 = 400 \\ x_4 = 500 - x_5 \\ x_5 & \text{is free} \end{cases}$$

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Again, real world constraints make the solution set smaller. x_4 cannot be negative because there cannot be a negative number of cars passing through a branch. So $0 \le x_5 \le 500$.

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