Row reduction and echelon forms

Danny W. Crytser

March 25, 2014



▲ロト ▲暦 ▶ ▲ 臣 ▶ ▲ 臣 ● 今へで

Today's lecture

Dan Crytser Row reduction and echelon forms

æ

Yesterday we sort of saw a way to solve systems of linear equations by manipulating rows in the affiliated augmented matrix.

Yesterday we sort of saw a way to solve systems of linear equations by manipulating rows in the affiliated augmented matrix. A lot of arbitrary decisions on what operations to perform were made. Yesterday we sort of saw a way to solve systems of linear equations by manipulating rows in the affiliated augmented matrix. A lot of arbitrary decisions on what operations to perform were made. Today we will make these choices seem a lot less arbitrary, refining method into a *row reduction algorithm*. Yesterday we sort of saw a way to solve systems of linear equations by manipulating rows in the affiliated augmented matrix. A lot of arbitrary decisions on what operations to perform were made. Today we will make these choices seem a lot less arbitrary, refining method into a *row reduction algorithm*. This will allow us to easily determine if a given system is consistent, and it will tell us how best to describe the solution set. The algorithm we will describe involves a lot of manipulation of the *leading entries* of rows of matrices.

The algorithm we will describe involves a lot of manipulation of the *leading entries* of rows of matrices. The *leading entry* of a nonzero row of a matrix is the leftmost nonzero entry in that row.

The algorithm we will describe involves a lot of manipulation of the *leading entries* of rows of matrices. The *leading entry* of a nonzero row of a matrix is the leftmost nonzero entry in that row.

Example Consider the matrix $\left|\begin{array}{cccc} 0 & 7 & 0 & 3 \\ 1 & 3 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array}\right|.$

The algorithm we will describe involves a lot of manipulation of the *leading entries* of rows of matrices. The *leading entry* of a nonzero row of a matrix is the leftmost nonzero entry in that row.

Example

Consider the matrix

$$\begin{bmatrix} 0 & 7 & 0 & 3 \\ 1 & 3 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

The leading entry of the first row is the 7 in the second column.

The algorithm we will describe involves a lot of manipulation of the *leading entries* of rows of matrices. The *leading entry* of a nonzero row of a matrix is the leftmost nonzero entry in that row.

Example

Consider the matrix

$$\begin{bmatrix} 0 & 7 & 0 & 3 \\ 1 & 3 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

- The leading entry of the first row is the 7 in the second column.
- The leading entry of the second row is the 1 in the first column.

The algorithm we will describe involves a lot of manipulation of the *leading entries* of rows of matrices. The *leading entry* of a nonzero row of a matrix is the leftmost nonzero entry in that row.

Example

Consider the matrix

$$\begin{bmatrix} 0 & 7 & 0 & 3 \\ 1 & 3 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

- The leading entry of the first row is the 7 in the second column.
- The leading entry of the second row is the 1 in the first column.
- The third row does not have a leading entry-they are all zero.

Definition

A matrix is in *echelon form* if it has the following three properties:

Definition

A matrix is in *echelon form* if it has the following three properties:

All nonzero rows are above any zero rows.

Definition

A matrix is in *echelon form* if it has the following three properties:

- All nonzero rows are above any zero rows.
- Each leading entry (leftmost nonzero entry) of a row is to the right of the leading entry of the row above it.

Definition

A matrix is in *echelon form* if it has the following three properties:

- All nonzero rows are above any zero rows.
- Each leading entry (leftmost nonzero entry) of a row is to the right of the leading entry of the row above it.
- I All entries in a column below a leading entry are zero.

Definition

A matrix is in echelon form if it has the following three properties:

- All nonzero rows are above any zero rows.
- Each leading entry (leftmost nonzero entry) of a row is to the right of the leading entry of the row above it.
- All entries in a column below a leading entry are zero.

A matrix is in *reduced echelon form* if it satisfies these three as well as:

Definition

A matrix is in echelon form if it has the following three properties:

- All nonzero rows are above any zero rows.
- Each leading entry (leftmost nonzero entry) of a row is to the right of the leading entry of the row above it.
- I All entries in a column below a leading entry are zero.

A matrix is in *reduced echelon form* if it satisfies these three as well as:

• The leading entry in each nonzero row is 1.

Definition

A matrix is in echelon form if it has the following three properties:

- All nonzero rows are above any zero rows.
- Each leading entry (leftmost nonzero entry) of a row is to the right of the leading entry of the row above it.
- I All entries in a column below a leading entry are zero.

A matrix is in *reduced echelon form* if it satisfies these three as well as:

- The leading entry in each nonzero row is 1.
- S Each leading 1 is the only nonzero entry in its column.

Example

Check out this matrix

$$\begin{bmatrix} 2 & 8 & 1 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Example

Check out this matrix

Is it in echelon form? reduced echelon form?

Example

Check out this matrix

$$\begin{bmatrix} 2 & 8 & 1 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Is it in echelon form? reduced echelon form?

Same question.

Example

Check out this matrix

$$\begin{array}{cccccccc} 2 & 8 & 1 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{array}$$

Is it in echelon form? reduced echelon form?

Same question.

$$\left[\begin{array}{rrrrr}1 & 0 & 0 & 7\\0 & 1 & 0 & 7\\0 & 0 & 1 & 0\end{array}\right]$$

Example

Check out this matrix

$$\begin{array}{cccccccc} 2 & 8 & 1 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{array}$$

Is it in echelon form? reduced echelon form?

Same question.

The elementary row operations on matrices are:

The elementary row operations on matrices are:

Add a multiple of one row to another.

The elementary row operations on matrices are:

- Add a multiple of one row to another.
- Switch the positions of two rows.

The elementary row operations on matrices are:

- Add a multiple of one row to another.
- Switch the positions of two rows.
- Scale any row by any nonzero number.

The elementary row operations on matrices are:

- Add a multiple of one row to another.
- Switch the positions of two rows.
- Scale any row by any nonzero number.

Definition

We say that matrices A and B are *row-equivalent* if B is obtained by performing elementary operations on A.

The elementary row operations on matrices are:

- Add a multiple of one row to another.
- Switch the positions of two rows.
- Scale any row by any nonzero number.

Definition

We say that matrices A and B are *row-equivalent* if B is obtained by performing elementary operations on A. (Or vice versa: row operations are reversible.)

Example

The matrices

$$A = \left[\begin{array}{rrr} 1 & 1 & 2 \\ 2 & 2 & 4 \end{array} \right] \text{ and } B = \left[\begin{array}{rrr} 1 & 1 & 2 \\ 0 & 0 & 0 \end{array} \right]$$

are row-equivalent:

The elementary row operations on matrices are:

- Add a multiple of one row to another.
- Switch the positions of two rows.
- Scale any row by any nonzero number.

Definition

We say that matrices A and B are *row-equivalent* if B is obtained by performing elementary operations on A. (Or vice versa: row operations are reversible.)

Example

The matrices

$$A = \left[\begin{array}{rrr} 1 & 1 & 2 \\ 2 & 2 & 4 \end{array} \right] \text{ and } B = \left[\begin{array}{rrr} 1 & 1 & 2 \\ 0 & 0 & 0 \end{array} \right]$$

are row-equivalent: we can add -2 times the first row of A to the second row of A to obtain B.

Why row-equivalence matters

Dan Crytser Row reduction and echelon forms

Theorem

Suppose that A and B are the augmented matrices of two systems of linear equations. If A and B are row-equivalent, then the two systems have the same solution sets.

Theorem

Suppose that A and B are the augmented matrices of two systems of linear equations. If A and B are row-equivalent, then the two systems have the same solution sets.

The matrices

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & 2 & 4 \end{bmatrix} \text{ and } \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

are row-equivalent.

Theorem

Suppose that A and B are the augmented matrices of two systems of linear equations. If A and B are row-equivalent, then the two systems have the same solution sets.

The matrices

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & 2 & 4 \end{bmatrix} \text{ and } \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

are row-equivalent. So

$$x + y = 2$$
$$2x + 2y = 4$$

and

$$x + y = 2$$

have the same solution sets
Theorem

Suppose that A and B are the augmented matrices of two systems of linear equations. If A and B are row-equivalent, then the two systems have the same solution sets.

The matrices

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & 2 & 4 \end{bmatrix} \text{ and } \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

are row-equivalent. So

$$x + y = 2$$
$$2x + 2y = 4$$

and

$$x + y = 2$$

have the same solution sets (line through (0,2) and (2,0)).

Dan Crytser Row reduction and echelon forms

Finding echelon forms is useful because if a system has augmented matrix in reduced echelon form, we will see that it is very easy to describe the solution set of the system.

Finding echelon forms is useful because if a system has augmented matrix in reduced echelon form, we will see that it is very easy to describe the solution set of the system.

Theorem

Let A be a matrix. Then there is a unique matrix U in reduced echelon form which is row-equivalent to A.

If A is a matrix, then we call the unique U in this theorem the reduced echoelon form of A.

Finding echelon forms is useful because if a system has augmented matrix in reduced echelon form, we will see that it is very easy to describe the solution set of the system.

Theorem

Let A be a matrix. Then there is a unique matrix U in reduced echelon form which is row-equivalent to A.

If A is a matrix, then we call the unique U in this theorem the *reduced echoelon form of* A. Our goal in this section is to develop a technique for systematically transforming matrices, via elementary row operations, to reduced echelon form.

A *pivot position* in a matrix A is a location (row and column) in A that corresponds to a leading 1 in the reduced echelon form of A.

A pivot position in a matrix A is a location (row and column) in A that corresponds to a leading 1 in the reduced echelon form of A. A pivot column is a column of A that contains a pivot position.

A pivot position in a matrix A is a location (row and column) in A that corresponds to a leading 1 in the reduced echelon form of A. A pivot column is a column of A that contains a pivot position.

Example

The reduced echelon form of
$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 2 & 4 \end{bmatrix}$$
 is
$$U = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}.$$

A pivot position in a matrix A is a location (row and column) in A that corresponds to a leading 1 in the reduced echelon form of A. A pivot column is a column of A that contains a pivot position.

Example

The reduced echelon form of
$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 2 & 4 \end{bmatrix}$$
 is
 $U = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$. The only leading one in the reduced

form is in the first column and first row.

echelon

A pivot position in a matrix A is a location (row and column) in A that corresponds to a leading 1 in the reduced echelon form of A. A pivot column is a column of A that contains a pivot position.

Example

The reduced echelon form of
$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 2 & 4 \end{bmatrix}$$
 is
$$U = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$
. The only leading one in the reduced echelon

form is in the first column and first row. So the only pivot position of A is in the first row and first column, and the only pivot column of A is the first column.

Let

$$A = \begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

< ∃ >

э

Let

$$A = \begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

We are going to find the reduced echelon form of A using the row reduction algorithm.

Let

$$A = \begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

We are going to find the reduced echelon form of A using the row reduction algorithm.

Step 1: Begin with the leftmost nonzero column. This is a pivot column. There is a pivot position at the top of this column.

Let

$$A = \begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

We are going to find the reduced echelon form of A using the row reduction algorithm.

Step 1: Begin with the leftmost nonzero column. This is a pivot column. There is a pivot position at the top of this column.

Step 2: Swap rows to make sure there is a nonzero entry in this position.

Let

$$A = \begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

We are going to find the reduced echelon form of A using the row reduction algorithm.

Step 1: Begin with the leftmost nonzero column. This is a pivot column. There is a pivot position at the top of this column.

Step 2: Swap rows to make sure there is a nonzero entry in this position.

$$A = \begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 3:

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 3: Use row replacement to create zeros in positions below the pivot positions. (Add multiples of the first row to the rows containing zeros in the first column.)

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 3: Use row replacement to create zeros in positions below the pivot positions. (Add multiples of the first row to the rows containing zeros in the first column.) Here, we add 1 times the first row to the second row, and 2 times the first row to the third row.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 3: Use row replacement to create zeros in positions below the pivot positions. (Add multiples of the first row to the rows containing zeros in the first column.) Here, we add 1 times the first row to the second row, and 2 times the first row to the third row.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 3: Use row replacement to create zeros in positions below the pivot positions. (Add multiples of the first row to the rows containing zeros in the first column.) Here, we add 1 times the first row to the second row, and 2 times the first row to the third row.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Now below the first pivot position there are no nonzero entries.



$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 4: Now we ignore the row containing the first pivot position and every row above it, and we repeat steps 1-3 to the matrix that remains.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 4: Now we ignore the row containing the first pivot position and every row above it, and we repeat steps 1 - 3 to the matrix that remains. The second column is now the pivot column, and the pivot position is in the second row, second column.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 4: Now we ignore the row containing the first pivot position and every row above it, and we repeat steps 1 - 3 to the matrix that remains. The second column is now the pivot column, and the pivot position is in the second row, second column. There is a nonzero entry in this position already.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

Step 4: Now we ignore the row containing the first pivot position and every row above it, and we repeat steps 1-3 to the matrix that remains. The second column is now the pivot column, and the pivot position is in the second row, second column. There is a nonzero entry in this position already. We add $\frac{-5}{2}$ times the second row to the third row, and $\frac{3}{2}$ times the second row to the fourth row.

Step 4: Now we ignore the row containing the first pivot position and every row above it, and we repeat steps 1-3 to the matrix that remains. The second column is now the pivot column, and the pivot position is in the second row, second column. There is a nonzero entry in this position already. We add $\frac{-5}{2}$ times the second row to the third row, and $\frac{3}{2}$ times the second row to the fourth row.

Now we ignore the two top rows and look at the matrix that remains. The leftmost nonzero column is the fourth column. We repeat steps 1-3: all that we have to do is interchange the third and fourth rows.

Now we ignore the two top rows and look at the matrix that remains. The leftmost nonzero column is the fourth column. We repeat steps 1-3: all that we have to do is interchange the third and fourth rows.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -5 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 0 & 0 & -5 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Now the matrix is in *echelon form*. This completes steps 1 - 4.

Now we ignore the two top rows and look at the matrix that remains. The leftmost nonzero column is the fourth column. We repeat steps 1-3: all that we have to do is interchange the third and fourth rows.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -5 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 0 & 0 & -5 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Now the matrix is in *echelon form*. This completes steps 1 - 4.

We transform this into reduced echelon form:

We transform this into reduced echelon form: all the leading entries should be equal to 1, and the columns containing the leading entries only have 0s, except for the leading entries.

We transform this into reduced echelon form: all the leading entries should be equal to 1, and the columns containing the leading entries only have 0s, except for the leading entries. **Step 5**: Beginning with the rightmost pivot, create zeros above each pivot position. If necessary, first scale rows containing pivot positions to make the pivots equal 1.

We transform this into reduced echelon form: all the leading entries should be equal to 1, and the columns containing the leading entries only have 0s, except for the leading entries. **Step 5**: Beginning with the rightmost pivot, create zeros above each pivot position. If necessary, first scale rows containing pivot positions to make the pivots equal 1.

We scale the third row by $\frac{-1}{5}$, then add 6 times this new third row to the second row and 9 times the new third row to the first row.

We transform this into reduced echelon form: all the leading entries should be equal to 1, and the columns containing the leading entries only have 0s, except for the leading entries. **Step 5**: Beginning with the rightmost pivot, create zeros above each pivot position. If necessary, first scale rows containing pivot positions to make the pivots equal 1.

We scale the third row by $\frac{-1}{5}$, then add 6 times this new third row to the second row and 9 times the new third row to the first row.

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 0 & 0 & -5 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 5 & 0 & -7 \\ 0 & 2 & 4 & 0 & -6 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} .$$

Dan Crytser

Dan Crytser Row reduction and echelon forms
The next pivot position is in the second row, second column.

The next pivot position is in the second row, second column. We scale the second row by $\frac{1}{2}$ to get a 1 in the pivot position, then add -4 times this new second row to the first row to eliminate the 4 above the pivot position.

The next pivot position is in the second row, second column. We scale the second row by $\frac{1}{2}$ to get a 1 in the pivot position, then add -4 times this new second row to the first row to eliminate the 4 above the pivot position.

$$\begin{bmatrix} 1 & 4 & 5 & 0 & -7 \\ 0 & 2 & 4 & 0 & -6 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -3 & 0 & 5 \\ 0 & 1 & 2 & 0 & -3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

This matrix is in *reduced* echelon form: the leading entries are 1, no nonzero entries above the leading entries.

The next pivot position is in the second row, second column. We scale the second row by $\frac{1}{2}$ to get a 1 in the pivot position, then add -4 times this new second row to the first row to eliminate the 4 above the pivot position.

$$\begin{bmatrix} 1 & 4 & 5 & 0 & -7 \\ 0 & 2 & 4 & 0 & -6 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -3 & 0 & 5 \\ 0 & 1 & 2 & 0 & -3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

This matrix is in *reduced* echelon form: the leading entries are 1, no nonzero entries above the leading entries. The three pivot positions are: first row/first column, second row/second column, and third row/fourth column.

Forward and backward phases of the row reduction algorithm

We have just described the row reduction algorithm.

Steps 1 – 4 are called the *forward phase* of the row reduction algorithm.

 Steps 1 – 4 are called the *forward phase* of the row reduction algorithm. They transform a matrix into (possibly non-reduced) echelon form.

- Steps 1 4 are called the *forward phase* of the row reduction algorithm. They transform a matrix into (possibly non-reduced) echelon form.
- Step 5 is called the *backward phase* of the algorithm.

- Steps 1 4 are called the *forward phase* of the row reduction algorithm. They transform a matrix into (possibly non-reduced) echelon form.
- Step 5 is called the *backward phase* of the algorithm. It converts the echelon form into a reduced echelon form.

Solutions to linear systems

We want to use the row reduction algorithm to solve systems of linear equations.

Solutions to linear systems

We want to use the row reduction algorithm to solve systems of linear equations. The reduced echelon form of the augmented matrix of a linear system gives a tidy description of the solution set.

Solutions to linear systems

We want to use the row reduction algorithm to solve systems of linear equations. The reduced echelon form of the augmented matrix of a linear system gives a tidy description of the solution set.

Example

The augmented matrix

$$\begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

corresponds to the system

$$-3x_{2} - 6x_{3} + 4x_{4} = 9$$

$$-x_{1} - 2x_{2} - x_{3} + 3x_{4} = 1$$

$$-2x_{1} - 3x_{2} + 3x_{4} = -1$$

$$x_{1} + 4x_{2} + 5x_{3} - 9x_{4} = -7$$
Dan Crytser
Row reduction and echelon forms

Example

We converted

$$\begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -3 & 0 & 5 \\ 0 & 1 & 2 & 0 & -3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Example

We converted

$$\begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -3 & 0 & 5 \\ 0 & 1 & 2 & 0 & -3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

This echelon form corresponds to the system

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

< ∃ >

э

When dealing with the system

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

we sort the variables x_1, x_2, x_3, x_4 into two categories.

When dealing with the system

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

we sort the variables x_1, x_2, x_3, x_4 into two categories.

The variables corresponding to pivot positions in the matrix are basic variables:

When dealing with the system

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

we sort the variables x_1, x_2, x_3, x_4 into two categories.

• The variables corresponding to pivot positions in the matrix are *basic variables*: in this case x_1, x_2, x_4 .

When dealing with the system

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

we sort the variables x_1, x_2, x_3, x_4 into two categories.

- The variables corresponding to pivot positions in the matrix are *basic variables*: in this case x_1, x_2, x_4 .
- The other variables are called *free variables*: in this case: x₃ is free.

We have:

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

We have:

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

Basic variables: x_1, x_2, x_4 . Free variables: x_3 .

We have:

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

Basic variables: x_1, x_2, x_4 . Free variables: x_3 . We write the basic variables in terms of the free variables, and that describes the solution set:

$$\begin{cases} x_1 = 5 + 3x_3 \\ x_2 = -3 - 2x_3 \\ x_3 & \text{is free} \\ x_4 = 0 \end{cases}$$

We have:

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

Basic variables: x_1, x_2, x_4 . Free variables: x_3 . We write the basic variables in terms of the free variables, and that describes the solution set:

$$\begin{cases} x_1 = 5 + 3x_3 \\ x_2 = -3 - 2x_3 \\ x_3 & \text{is free} \\ x_4 = 0 \end{cases}$$

Any value of x_3 is permitted, and the other entries in the solution are dictated by the value of x_3

We have:

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

Basic variables: x_1, x_2, x_4 . Free variables: x_3 . We write the basic variables in terms of the free variables, and that describes the solution set:

$$\begin{cases} x_1 = 5 + 3x_3 \\ x_2 = -3 - 2x_3 \\ x_3 & \text{is free} \\ x_4 = 0 \end{cases}$$

Any value of x_3 is permitted, and the other entries in the solution are dictated by the value of x_3 We say that this is a *parametric description of the solution set*, where the free variable x_3 is the *parameter*-the thing which is allowed to vary.

Dan Crytser Row reduction and echelon forms

To summarize the preceding:

To summarize the preceding: The system

$$-3x_2 - 6x_3 + 4x_4 = 9$$

$$-x_1 - 2x_2 - x_3 + 3x_4 = 1$$

$$-2x_1 - 3x_2 + 3x_4 = -1$$

$$x_1 + 4x_2 + 5x_3 - 9x_4 = -7$$

is equivalent to the system

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

To summarize the preceding: The system

$$-3x_2 - 6x_3 + 4x_4 = 9$$

$$-x_1 - 2x_2 - x_3 + 3x_4 = 1$$

$$-2x_1 - 3x_2 + 3x_4 = -1$$

$$x_1 + 4x_2 + 5x_3 - 9x_4 = -7$$

is equivalent to the system

$$x_1 - 3x_3 = 5$$

 $x_2 + 2x_3 = -3$
 $x_4 = 0$

The solution set of both systems is described by:

$$\begin{array}{l} x_1 &= 5 + 3x_3 \\ x_2 &= -3 - 2x_3 \\ x_3 & \text{ is free} \\ x_4 &= 0 \end{array}$$

Existence/uniqueness with echelon forms

You might ask: why do we ever care about the echelon form of a matrix?

Existence/uniqueness with echelon forms

You might ask: why do we ever care about the echelon form of a matrix? The solution set is described using the *reduced echelon form* of the augmented matrix of the system.

You might ask: why do we ever care about the echelon form of a matrix? The solution set is described using the *reduced echelon form* of the augmented matrix of the system. That's true, and the echelon form doesn't describe the solutions of the system.

You might ask: why do we ever care about the echelon form of a matrix? The solution set is described using the *reduced echelon form* of the augmented matrix of the system. That's true, and the echelon form doesn't describe the solutions of the system. It answers existence/uniqueness questions though.

You might ask: why do we ever care about the echelon form of a matrix? The solution set is described using the *reduced echelon form* of the augmented matrix of the system. That's true, and the echelon form doesn't describe the solutions of the system. It answers existence/uniqueness questions though. **Existence**: the system has a solution if the echelon form of its augmented matrix has no rows like

$$\begin{bmatrix} 0 & 0 & \cdots & b \end{bmatrix}$$
 with $b \neq 0$

You might ask: why do we ever care about the echelon form of a matrix? The solution set is described using the *reduced echelon form* of the augmented matrix of the system. That's true, and the echelon form doesn't describe the solutions of the system. It answers existence/uniqueness questions though. **Existence**: the system has a solution if the echelon form of its

augmented matrix has no rows like

$$\begin{bmatrix} 0 & 0 & \cdots & b \end{bmatrix}$$
 with $b \neq 0$

Uniqueness: Assuming the system is consistent, then it has unique solution if every column (of the echelon form of its augmented matrix) *except the last* contains a leading entry.

You might ask: why do we ever care about the echelon form of a matrix? The solution set is described using the *reduced echelon form* of the augmented matrix of the system. That's true, and the echelon form doesn't describe the solutions of the system. It answers existence/uniqueness questions though. **Existence**: the system has a solution if the echelon form of its

augmented matrix has no rows like

$$\begin{bmatrix} 0 & 0 & \cdots & b \end{bmatrix}$$
 with $b \neq 0$

Uniqueness: Assuming the system is consistent, then it has unique solution if every column (of the echelon form of its augmented matrix) *except the last* contains a leading entry. Otherwise, it has infinitely many solutions.

Example

Suppose that we have a linear system whose augmented matrix we have reduced to the echelon form

$$\left[\begin{array}{rrrrr} 2 & 2 & 0 & 0 \\ 0 & 7 & -1 & 1 \\ 0 & 0 & 0 & 10 \end{array}\right]$$

Does there exist a solution to the system?
Example

Suppose that we have a linear system whose augmented matrix we have reduced to the echelon form

$$\left[\begin{array}{rrrrr} 2 & 2 & 0 & 0 \\ 0 & 7 & -1 & 1 \\ 0 & 0 & 0 & 10 \end{array}\right]$$

Does there exist a solution to the system? What about if the echelon form is

2	2	0	0]
0	7	-1	1
0	0	0	0

Example

Suppose that we have a linear system whose augmented matrix we have reduced to the echelon form

$$\left[\begin{array}{rrrrr} 2 & 2 & 0 & 0 \\ 0 & 7 & -1 & 1 \\ 0 & 0 & 0 & 10 \end{array}\right]$$

Does there exist a solution to the system? What about if the echelon form is

2	2	0	0
0	7	-1	1
0	0	0	0

In this case, is the solution unique?