# Row reduction and echelon forms 

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March 25, 2014


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Yesterday we sort of saw a way to solve systems of linear equations by manipulating rows in the affiliated augmented matrix. A lot of arbitrary decisions on what operations to perform were made. Today we will make these choices seem a lot less arbtirary, refining method into a row reduction algorithm. This will allow us to easily determine if a given system is consistent, and it will tell us how best to describe the solution set.

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\left[\begin{array}{llll}
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\end{array}\right]
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(1) The leading entry of the first row is the 7 in the second column.
(2) The leading entry of the second row is the 1 in the first column.
(3) The third row does not have a leading entry-they are all zero.

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(9) The leading entry in each nonzero row is 1 .
(6) Each leading 1 is the only nonzero entry in its column.

## Examples of echelon forms

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Check out this matrix

$$
\left[\begin{array}{llll}
2 & 8 & 1 & 0 \\
0 & 0 & 1 & 2 \\
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\end{array}\right]
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Same question.

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The matrices

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A=\left[\begin{array}{lll}
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are row-equivalent: we can add -2 times the first row of $A$ to the second row of $A$ to obtain $B$.

## Why row-equivalence matters

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## Theorem

Suppose that $A$ and $B$ are the augmented matrices of two systems of linear equations. If $A$ and $B$ are row-equivalent, then the two systems have the same solution sets.

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have the same solution sets (line through $(0,2)$ and $(2,0)$ ).

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## Theorem

Let $A$ be a matrix. Then there is a unique matrix $U$ in reduced echelon form which is row-equivalent to $A$.

If $A$ is a matrix, then we call the unique $U$ in this theorem the reduced echoelon form of $A$.

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If $A$ is a matrix, then we call the unique $U$ in this theorem the reduced echoelon form of $A$. Our goal in this section is to develop a technique for systematically transforming matrices, via elementary row operations, to reduced echelon form.

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The reduced echelon form of $A=\left[\begin{array}{lll}1 & 1 & 2 \\ 2 & 2 & 4\end{array}\right]$ is $U=\left[\begin{array}{lll}1 & 1 & 2 \\ 0 & 0 & 0\end{array}\right]$.

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$U=\left[\begin{array}{lll}1 & 1 & 2 \\ 0 & 0 & 0\end{array}\right]$. The only leading one in the reduced echelon form is in the first column and first row. So the only pivot position of $A$ is in the first row and first column, and the only pivot column of $A$ is the first column.

## Example: The row reduction algorithm

Let

$$
A=\left[\begin{array}{ccccc}
0 & -3 & -6 & 4 & 9 \\
-1 & -2 & -1 & 3 & 1 \\
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1 & 4 & 5 & -9 & -7
\end{array}\right]
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$A=\left[\begin{array}{ccccc}0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7\end{array}\right] \rightarrow\left[\begin{array}{ccccc}1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9\end{array}\right]$

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Step 3:

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Step 3: Use row replacement to create zeros in positions below the pivot positions. (Add multiples of the first row to the rows containing zeros in the first column.)

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Step 3: Use row replacement to create zeros in positions below the pivot positions. (Add multiples of the first row to the rows containing zeros in the first column.) Here, we add 1 times the first row to the second row, and 2 times the first row to the third row.

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Now below the first pivot position there are no nonzero entries.

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Step 4: Now we ignore the row containing the first pivot position and every row above it, and we repeat steps $1-3$ to the matrix that remains.

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$$

Now we ignore the two top rows and look at the matrix that remains. The leftmost nonzero column is the fourth column. We repeat steps $1-3$ : all that we have to do is interchange the third and fourth rows.

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\left[\begin{array}{ccccc}
1 & 4 & 5 & -9 & -7 \\
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Now the matrix is in echelon form. This completes steps $1-4$.

## Row reduction algorithm, ctd.

$$
\left[\begin{array}{ccccc}
1 & 4 & 5 & -9 & -7 \\
0 & 2 & 4 & -6 & -6 \\
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & -5 & 0
\end{array}\right]
$$

Now we ignore the two top rows and look at the matrix that remains. The leftmost nonzero column is the fourth column. We repeat steps $1-3$ : all that we have to do is interchange the third and fourth rows.

$$
\left[\begin{array}{ccccc}
1 & 4 & 5 & -9 & -7 \\
0 & 2 & 4 & -6 & -6 \\
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & -5 & 0
\end{array}\right] \rightarrow\left[\begin{array}{ccccc}
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We transform this into reduced echelon form:

## Row reduction algorithm, ctd.

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\left[\begin{array}{ccccc}
1 & 4 & 5 & -9 & -7 \\
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\end{array}\right]
$$

We transform this into reduced echelon form: all the leading entries should be equal to 1 , and the columns containing the leading entries only have 0s, except for the leading entries.

## Row reduction algorithm, ctd.

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\left[\begin{array}{ccccc}
1 & 4 & 5 & -9 & -7 \\
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Step 5: Beginning with the rightmost pivot, create zeros above each pivot position. If necessary, first scale rows containing pivot positions to make the pivots equal 1.

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Step 5: Beginning with the rightmost pivot, create zeros above each pivot position. If necessary, first scale rows containing pivot positions to make the pivots equal 1.
We scale the third row by $\frac{-1}{5}$, then add 6 times this new third row to the second row and 9 times the new third row to the first row.

## Row reduction algorithm, ctd.

$$
\left[\begin{array}{ccccc}
1 & 4 & 5 & -9 & -7 \\
0 & 2 & 4 & -6 & -6 \\
0 & 0 & 0 & -5 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right]
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0 & 0 & 0 & 0 & 0
\end{array}\right] \rightarrow\left[\begin{array}{ccccc}
1 & 4 & 5 & 0 & -7 \\
0 & 2 & 4 & 0 & -6 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right]
$$

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The next pivot position is in the second row, second column.

## Row reduction algorithm, ctd.

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\left[\begin{array}{ccccc}
1 & 4 & 5 & 0 & -7 \\
0 & 2 & 4 & 0 & -6 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right]
$$

The next pivot position is in the second row, second column. We scale the second row by $\frac{1}{2}$ to get a 1 in the pivot position, then add -4 times this new second row to the first row to eliminate the 4 above the pivot position.

## Row reduction algorithm, ctd.

$$
\left[\begin{array}{ccccc}
1 & 4 & 5 & 0 & -7 \\
0 & 2 & 4 & 0 & -6 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
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1 & 4 & 5 & 0 & -7 \\
0 & 2 & 4 & 0 & -6 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right] \rightarrow\left[\begin{array}{ccccc}
1 & 0 & -3 & 0 & 5 \\
0 & 1 & 2 & 0 & -3 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right]
$$

This matrixis in reduced echelon form: the leading entries are 1 , no nonzero entries above the leading entries.

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1 & 4 & 5 & 0 & -7 \\
0 & 2 & 4 & 0 & -6 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right] \rightarrow\left[\begin{array}{ccccc}
1 & 0 & -3 & 0 & 5 \\
0 & 1 & 2 & 0 & -3 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right]
$$

This matrixis in reduced echelon form: the leading entries are 1, no nonzero entries above the leading entries. The three pivot positions are: first row/first column, second row/second column, and third row/fourth column.

# Forward and backward phases of the row reduction algorithm 

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(1) Steps 1-4 are called the forward phase of the row reduction algorithm. They transform a matrix into (possibly non-reduced) echelon form.
(2) Step 5 is called the backward phase of the algorithm. It converts the echelon form into a reduced echelon form.

## Solutions to linear systems

We want to use the row reduction algorithm to solve systems of linear equations.

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## Example

The augmented matrix

$$
\left[\begin{array}{ccccc}
0 & -3 & -6 & 4 & 9 \\
-1 & -2 & -1 & 3 & 1 \\
-2 & -3 & 0 & 3 & -1 \\
1 & 4 & 5 & -9 & -7
\end{array}\right]
$$

corresponds to the system

$$
\begin{aligned}
&-3 x_{2}-6 x_{3}+4 x_{4}=9 \\
&-x_{1}-2 x_{2}-x_{3}+3 x_{4}=1 \\
&-2 x_{1}-3 x_{2}+3 x_{4}=-1 \\
& x_{1}+x_{\text {Dan }} x_{1}+5 x_{3}-5 x_{3}-9 x_{4}=-7 \\
& \text { Row reduction and echelon forms }
\end{aligned}
$$

Solutions to linear systems, ctd.

## Example

We converted

$$
\left[\begin{array}{ccccc}
0 & -3 & -6 & 4 & 9 \\
-1 & -2 & -1 & 3 & 1 \\
-2 & -3 & 0 & 3 & -1 \\
1 & 4 & 5 & -9 & -7
\end{array}\right] \rightarrow\left[\begin{array}{ccccc}
1 & 0 & -3 & 0 & 5 \\
0 & 1 & 2 & 0 & -3 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right]
$$

Solutions to linear systems, ctd.

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$$
\left[\begin{array}{ccccc}
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1 & 0 & -3 & 0 & 5 \\
0 & 1 & 2 & 0 & -3 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right]
$$

This echelon form corresponds to the system

$$
\begin{aligned}
x_{1}-3 x_{3} & =5 \\
x_{2}+2 x_{3} & =-3 \\
x_{4} & =0
\end{aligned}
$$

## Solutions to linear systems, ctd.

$$
\left[\begin{array}{ccccc}
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\end{array}\right]
$$

When dealing with the system

$$
\begin{aligned}
x_{1}-3 x_{3} & =5 \\
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x_{4} & =0
\end{aligned}
$$

we sort the variables $x_{1}, x_{2}, x_{3}, x_{4}$ into two categories.

## Solutions to linear systems, ctd.

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(1) The variables corresponding to pivot positions in the matrix are basic variables:

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we sort the variables $x_{1}, x_{2}, x_{3}, x_{4}$ into two categories.
(1) The variables corresponding to pivot positions in the matrix are basic variables: in this case $x_{1}, x_{2}, x_{4}$.
(2) The other variables are called free variables: in this case: $x_{3}$ is free.

## Solutions to linear systems, ctd.

We have:

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Basic variables: $x_{1}, x_{2}, x_{4}$. Free variables: $x_{3}$.

## Solutions to linear systems, ctd.

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x_{2}+2 x_{3} & =-3 \\
x_{4} & =0
\end{aligned}
$$

Basic variables: $x_{1}, x_{2}, x_{4}$. Free variables: $x_{3}$. We write the basic variables in terms of the free variables, and that describes the solution set:

$$
\left\{\begin{array}{cc}
x_{1}= & =5+3 x_{3} \\
x_{2}= & -3-2 x_{3} \\
x_{3} & \text { is free } \\
x_{4}= & 0
\end{array}\right.
$$

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\end{array}\right.
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Any value of $x_{3}$ is permitted, and the other entries in the solution are dictated by the value of $x_{3}$ We say that this is a parametric description of the solution set, where the free variable $x_{3}$ is the parameter-the thing which is allowed to vary.

## Solutions to linear systems, ctd.

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To summarize the preceding:

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-3 x_{2}-6 x_{3}+4 x_{4} & =9 \\
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x_{1}+4 x_{2}+5 x_{3}-9 x_{4} & =-7
\end{aligned}
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is equivalent to the system

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x_{1}-3 x_{3} & =5 \\
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x_{4} & =0
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$$

The solution set of both systems is described by:

$$
\left\{\begin{array}{cc}
x_{1} & =5+3 x_{3} \\
x_{2}=-3-2 x_{3} \\
x_{3} & \text { is free } \\
x_{4} & =0
\end{array}\right.
$$

## Existence/uniqueness with echelon forms

You might ask: why do we ever care about the echelon form of a matrix?

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Existence: the system has a solution if the echelon form of its augmented matrix has no rows like

$$
\left[\begin{array}{llll}
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Uniqueness: Assuming the system is consistent, then it has unique solution if every column (of the echelon form of its augmented matrix) except the last contains a leading entry.

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Uniqueness: Assuming the system is consistent, then it has unique solution if every column (of the echelon form of its augmented matrix) except the last contains a leading entry. Otherwise, it has infinitely many solutions.

## Example: existence and uniqueness with echelon forms

## Example

Suppose that we have a linear system whose augmented matrix we have reduced to the echelon form

$$
\left[\begin{array}{cccc}
2 & 2 & 0 & 0 \\
0 & 7 & -1 & 1 \\
0 & 0 & 0 & 10
\end{array}\right]
$$

Does there exist a solution to the system?

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\end{array}\right]
$$

In this case, is the solution unique?

